

Processes

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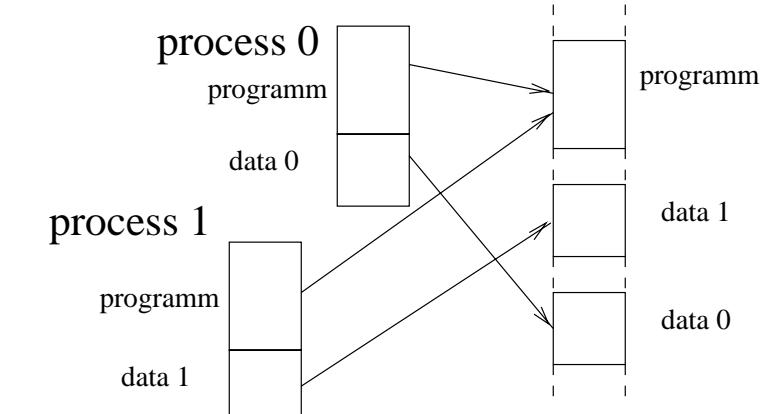
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Process creation

```
$pid=fork();
if ($pid == 0)
{ ..... child ..... }
elsif ($pid > 0)
{ ..... parent ..... }
else
{ ..... error ..... }
```

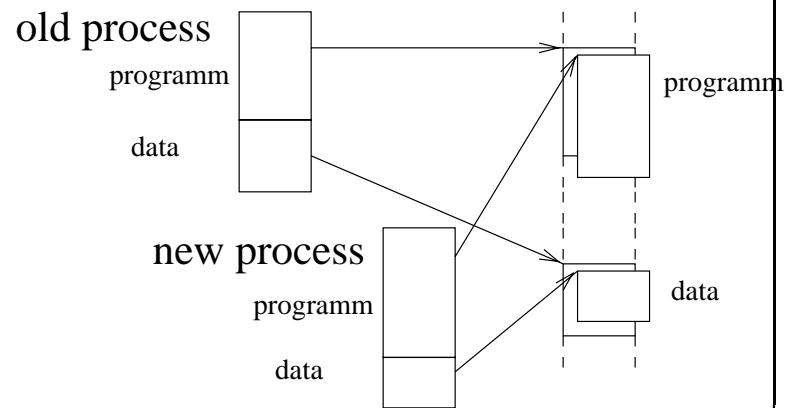
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Process memory



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Function – exec



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Signals

```
signal(SIGQUIT,SIG_DFL); /* reset to default handling */  
signal(SIGQUIT,SIG_IGN); /* ignore signal */  
signal(SIGQUIT,proc); /* set custom handler */  
kill(pid,SIGQUIT); /* send signal */  
void proc( int sig ) { ... } /* example signal handler */
```

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Waiting for a signal

```
int pause(void);
```

`pause()` suspends the calling process until it receives a signal. The signal must be one that is not currently set to be ignored by the calling process.

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SIGHUP 1 – hangup
SIGINT 2 – interrupt (rubout)
SIGQUIT 3 – quit (ASCII FS)
SIGILL 4 – illegal instruction (not reset when caught)
SIGTRAP 5 – trace trap (not reset when caught)
SIGIOT 6 – IOT instruction
SIGABRT 6 – used by abort, replace SIGIOT in the future
SIGEMT 7 – EMT instruction
SIGFPE 8 – floating point exception
SIGKILL 9 – kill (cannot be caught or ignored)
SIGBUS 10 – bus error
SIGSEGV 11 – segmentation violation
SIGSYS 12 – bad argument to system call
SIGPIPE 13 – write on a pipe with no one to read it
SIGALRM 14 – alarm clock
SIGTERM 15 – software termination signal from kill
SIGUSR1 16 – user defined signal 1

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Waiting for a child

```
pid_t waitpid(pid_t pid, int *stat_loc, int options);
```

pid – ID of the process

stat_loc – where to store the exit status

options – options:

WCONTINUED – report also continued processes

WNOHANG – do not suspend execution of the calling process

WNOWAIT – we wish to wait again for the same process

WUNTRACED – report also stopped processes

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